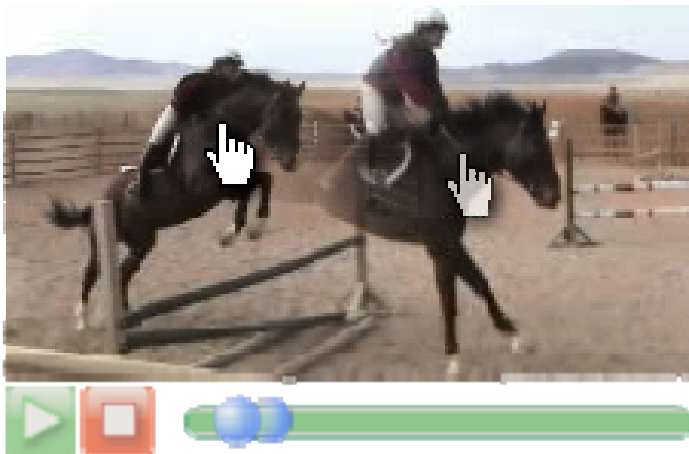


# Video Browsing By Direct Manipulation



Pierre Dragicevic  
Gonzalo Ramos  
Jacobó Bibliowitcz  
Derek Nowrouzezahrai  
Ravin Balakrishnan  
Karan Singh

dgp, University of Toronto  
INRIA, France

# Video Browsing By Direct Manipulation

- Sample Scenario



# Direct Manipulation

- **Shneiderman (1974, 1982)**
  - Continuous representation of objects
  - Rapid, incremental, reversible actions
  - Easy to learn, efficient, less errors
- **Hutchins, Hollan & Norman (1985)**
  - Low cognitive effort needed to manipulate the system and evaluate the results
  - Feeling of direct engagement

# Directness

- Hutchins, Hollan & Norman (1985, cont'd)
  - How well the input language of the GUI matches its output language
- Michel Beaudouin-Lafon (2000)
  - Degree of indirection
  - Degree of compatibility
  - Degree of integration

he mouse button is released. The figure  
e of indirection describes a continuum  
ulation (lower-left corner) and indirect  
right corner).

ration measures the ratio between the  
freedom (DOF) provided by the logical  
it and the number of DOFs captured by  
his term comes from the notion of  
]: some tasks are performed more  
the various DOFs are controlled  
a single device. A scrollbar is a 1D  
d by a 2D mouse, therefore its degree of  
he degree of integration can be larger  
rotation angles with a 2D mouse [16]



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he degree of integration can be larger  
rotation angles with a 2D mouse [16]



# Direct Manipulation

## As a Mapping Problem

- We already have a visual representation of objects of interest
- We want to be able to manipulate them
- Mapping user's gestures with existing visual motion



# Direct Manipulation

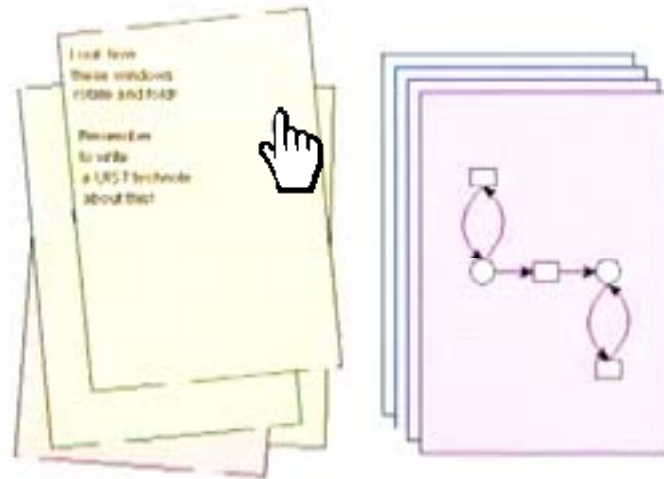
## As a Mapping Problem



- **User's Gesture Space:**
  - 2D mouse translations + buttons



- **Screen Motion Space:**
  - Any observable motion on the screen



2D translations  $\rightarrow$  2D translations + 1D rotations [Beaudouin-Lafon 01]

# Direct Manipulation

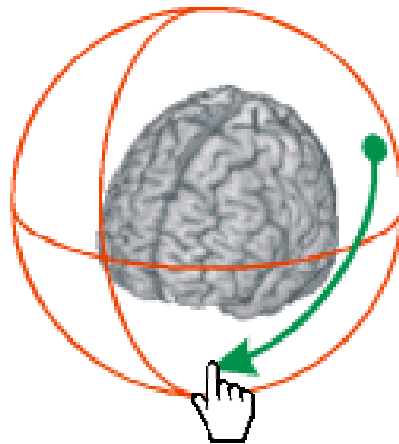
## As a Mapping Problem



- User's Gesture Space:
  - 2D mouse translations + buttons



- Screen Motion Space:
  - Any observable motion on the screen



2D translations  $\rightarrow$  3D rotations [Shoemake 92]

# Direct Manipulation

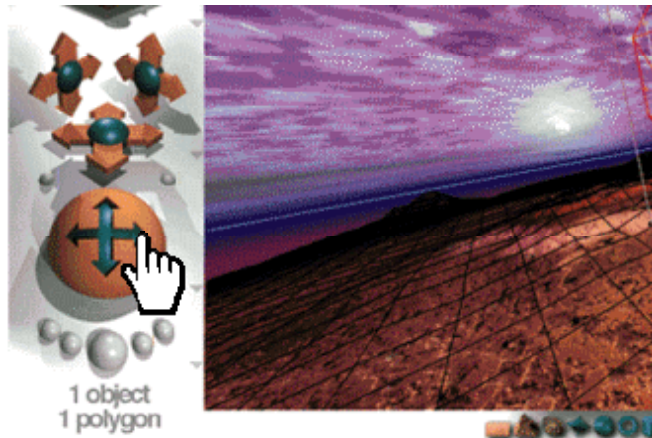
## As a Mapping Problem



- User's Gesture Space:
  - 2D mouse translations + buttons



- Screen Motion Space:
  - Any observable motion on the screen



2D translations  $\rightarrow$  6DOF rigid motions



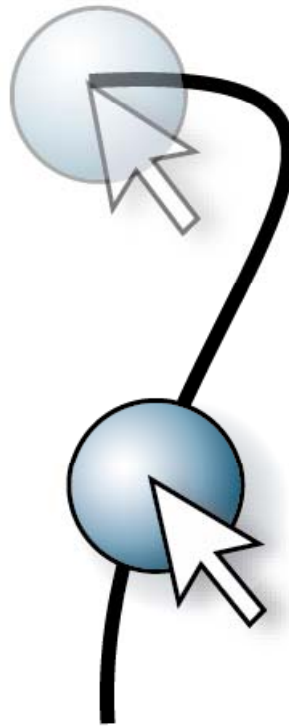
# Direct Manipulation

## As a Mapping Problem

- Control of High-Dimensional Motion Spaces:
  - Lots of Work
- Control of Low-Dimensional Motion Spaces:
  - Almost no Work
- 1-DOF Direct Manipulation

# Curvilinear Dragging

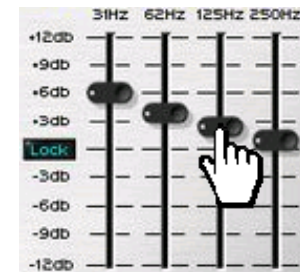
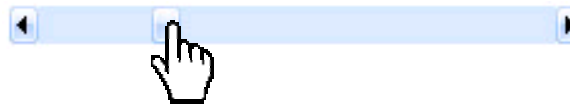
= Manipulating an object whose translation is constrained to a curve



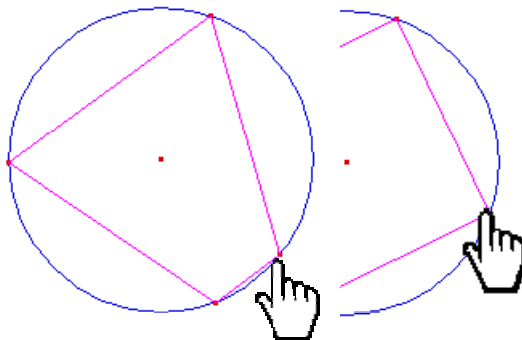
# Curvilinear Dragging

= Manipulating an object whose translation is constrained to a curve

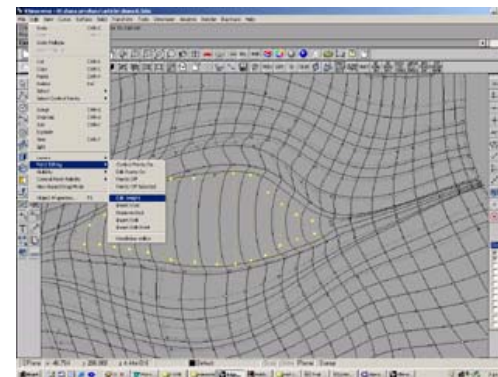
- Straight lines:



- Other:



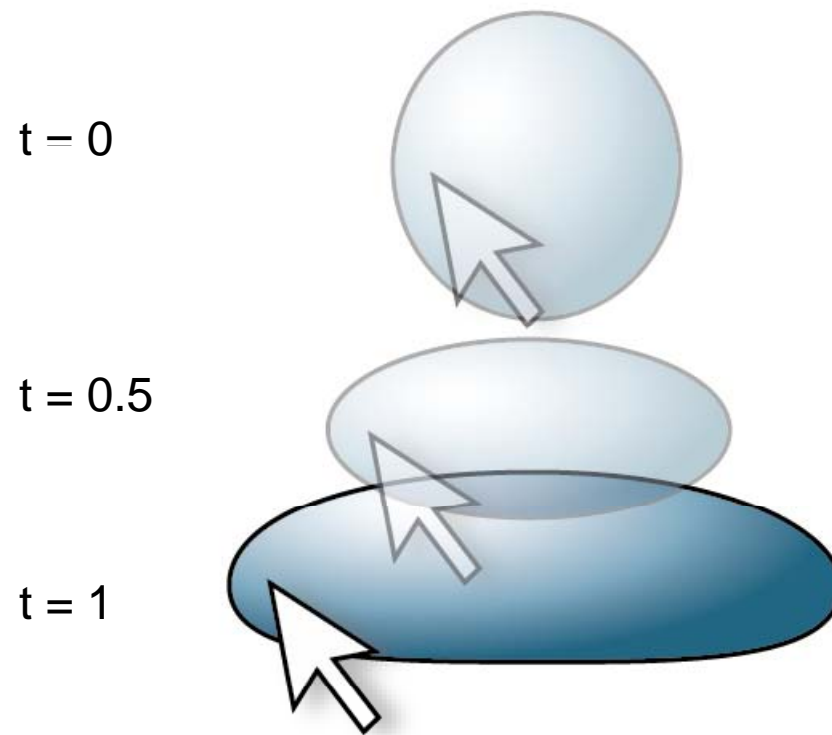
Cabri Géomètre



Autodesk Maya

# Flow Dragging

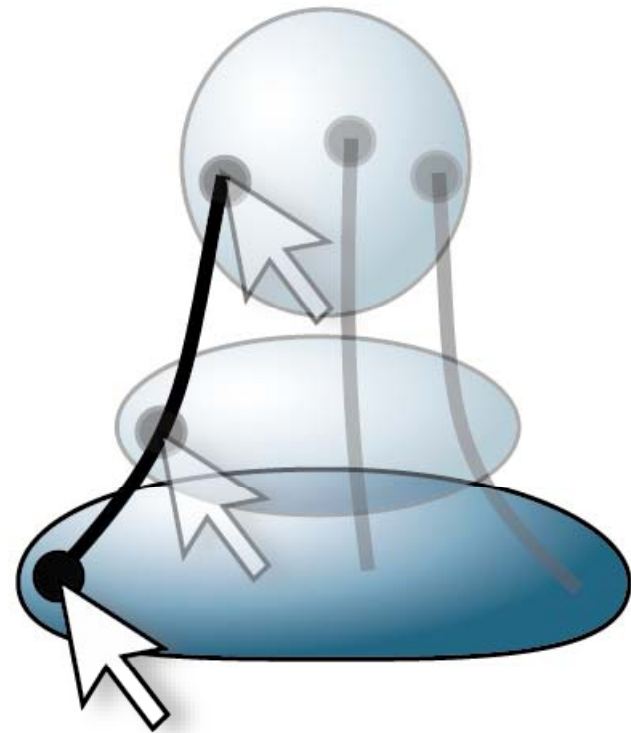
= Manipulating an object whose motion is constrained to a 1-D parameter



# Flow Dragging

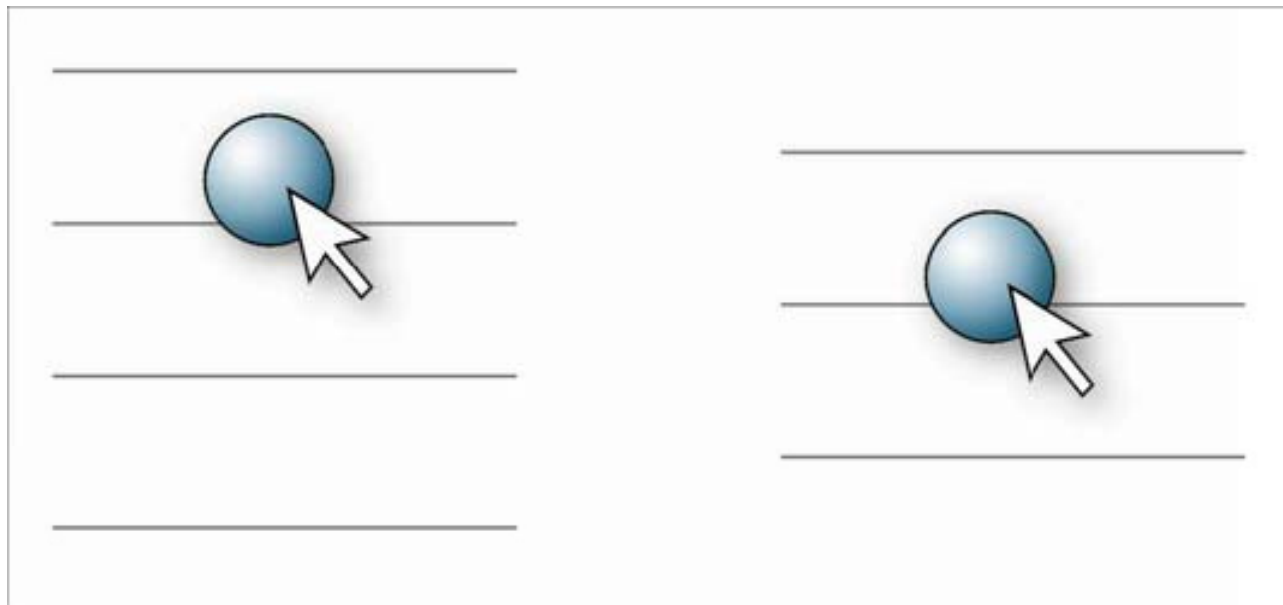
= Manipulating an object whose motion is constrained to a 1-D parameter

- Equivalent to curvilinear dragging on a family of curves



# Relative Dragging

= Manipulating an object's relative motion ("induced motion")



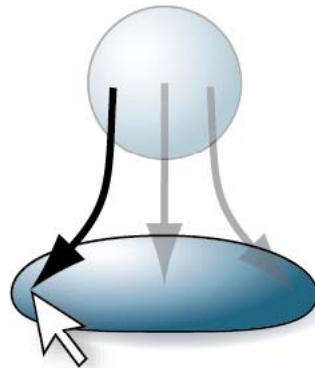
# RFD

## Relative Flow Dragging

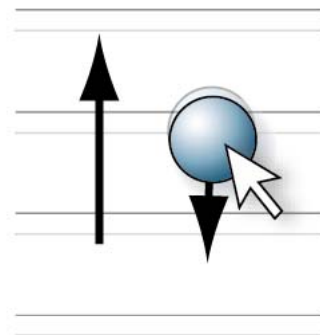
Curvilinear  
Dragging



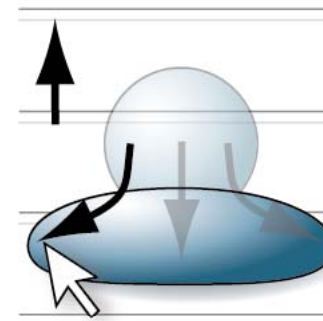
Flow  
Dragging



Relative  
Dragging



**RFD**



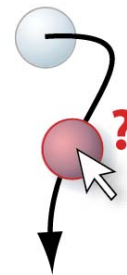
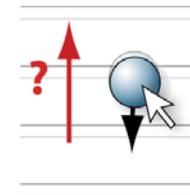
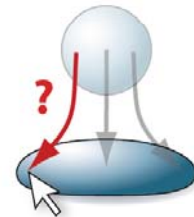
# Supporting RFD on Video Clips

- **Extracting motions**

- **Objects motion**

- **Background motion**

- **Supporting Curvilinear Dragging**





# Extracting Motions from Videos

- Manual Annotation vs. Automatic
- Object tracking vs. Optical flow
  - Scale Invariant Feature Transforms (SIFT) [Lowe 2004]

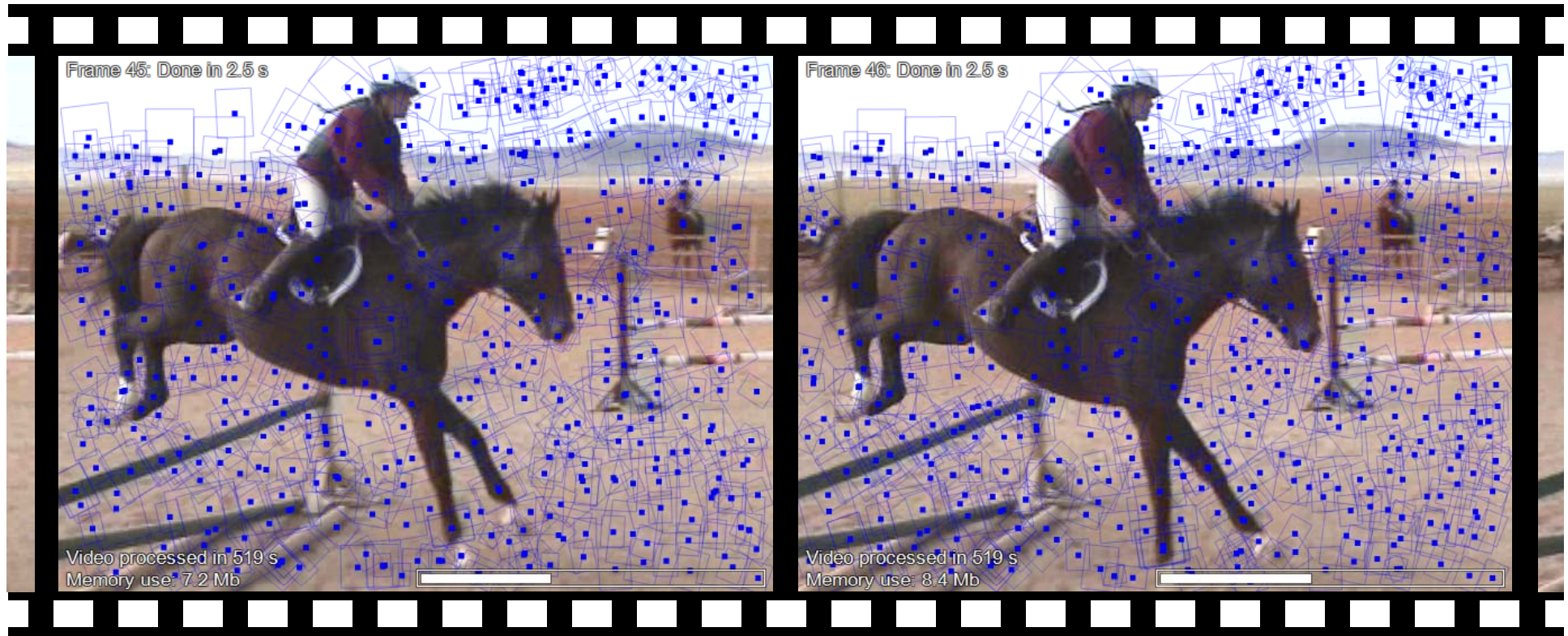


# Extracting Motions from Videos



# Extracting Motions from Videos

## 1. Feature Detection [Lowe 2004]





# Extracting Motions from Videos

1. Feature Detection
2. Feature Matching [Lowe 2004]



Feature Motions

# Extracting Motions from Videos

1. Feature Detection
2. Feature Matching
3. **Interpolation**



Feature Motions



Optical Flow

# Extracting Motions from Videos

1. Feature Detection
3. Feature Matching
4. Interpolation
5. Trajectory Construction



Feature Motions



“Pixel” Trajectories



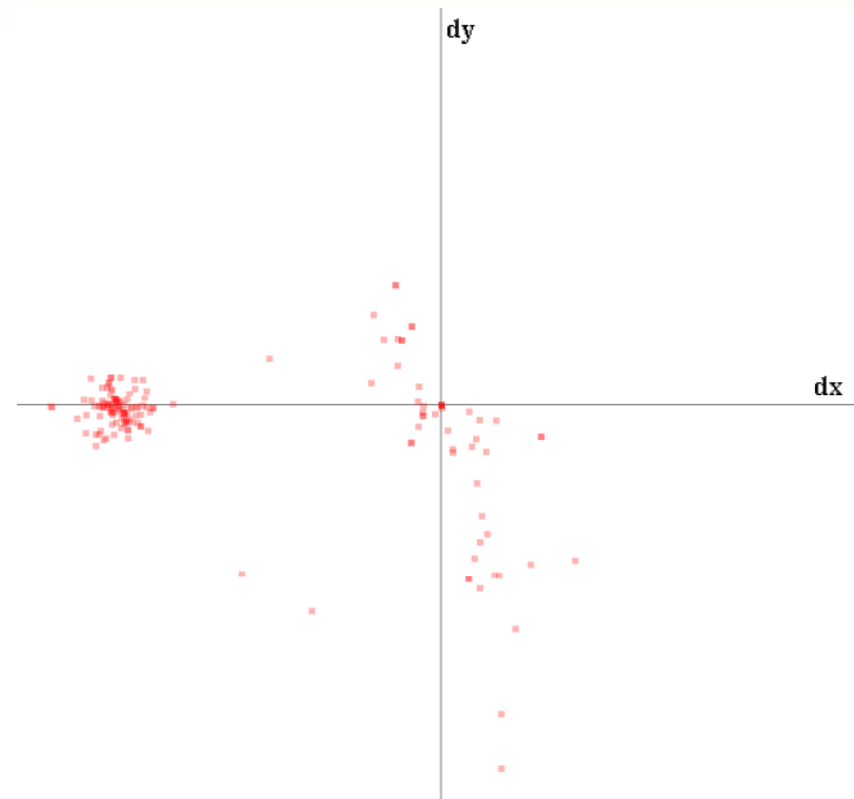
# Extracting Motions from Videos

1. Feature Detection
3. Feature Matching
4. Interpolation
5. Trajectory Construction

2b. Background Motion Estimation



Feature Motions

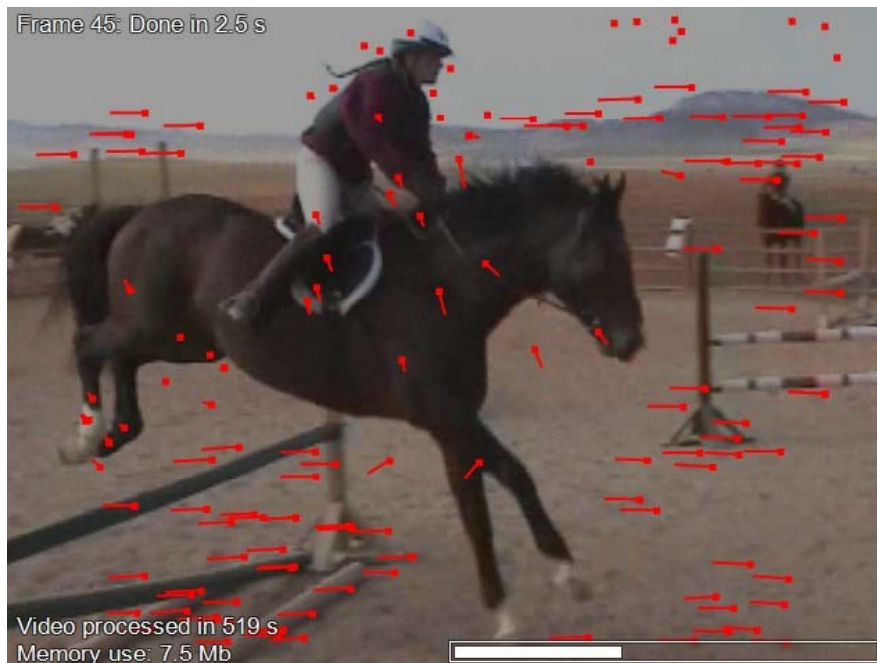


Feature Motions Plot

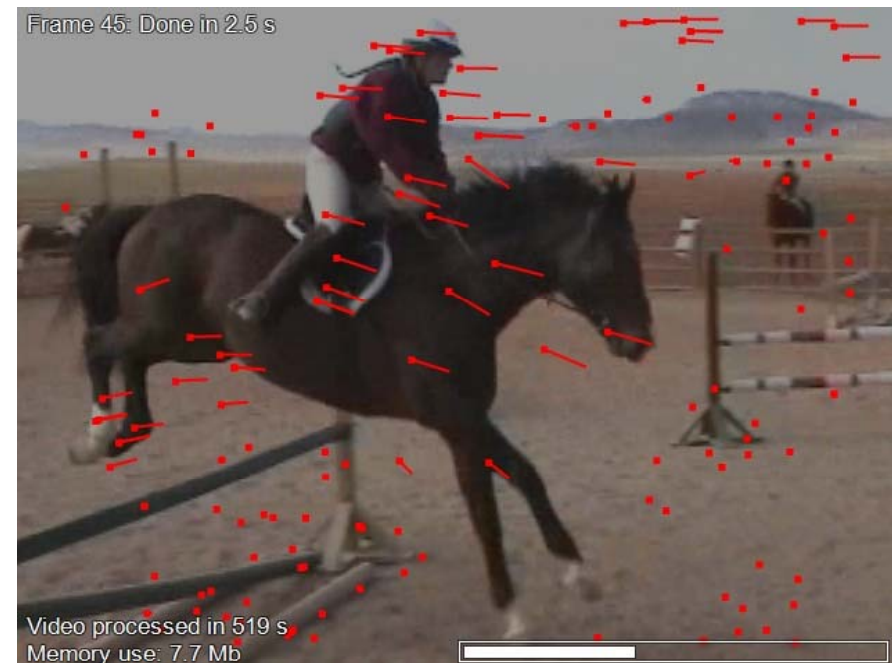
# Extracting Motions from Videos

1. Feature Detection
2. Feature Matching
3. Interpolation
4. Trajectory Construction

- { 2b. Background Motion Estimation  
2c. Background Motion Compensation



**Absolute** Feature Motions



**Relative** Feature Motions



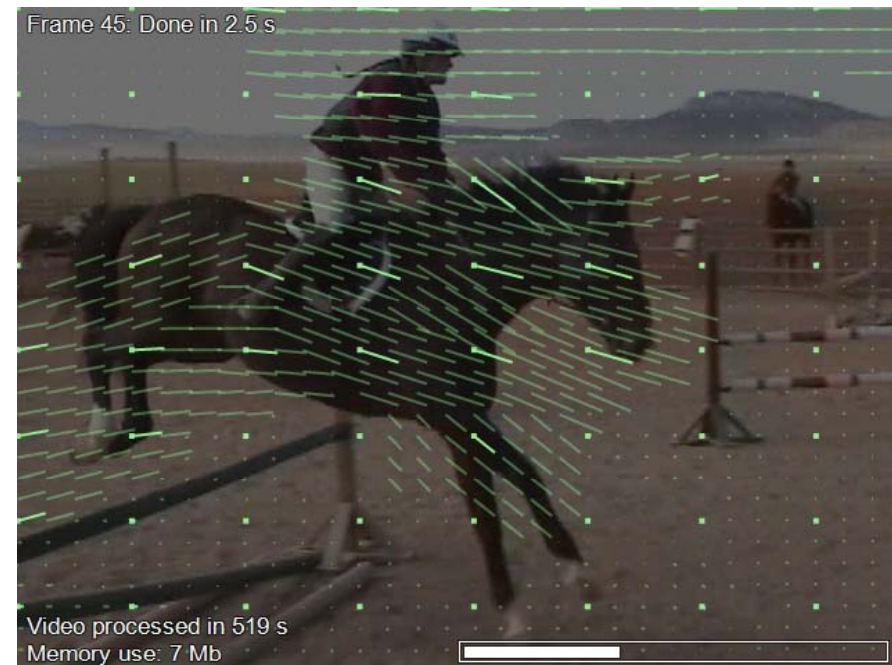
# Extracting Motions from Videos

1. Feature Detection
2. Feature Matching
3. Interpolation
4. Trajectory Construction

- 2b. Background Motion Estimation
- 2c. Background Motion Compensation



**Absolute** Optical Flow

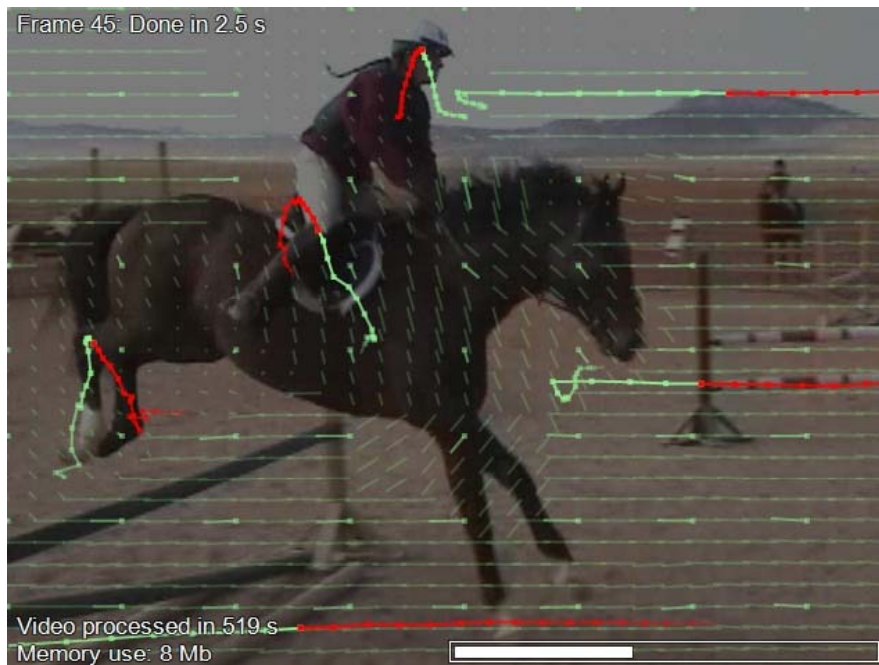


**Relative** Optical Flow

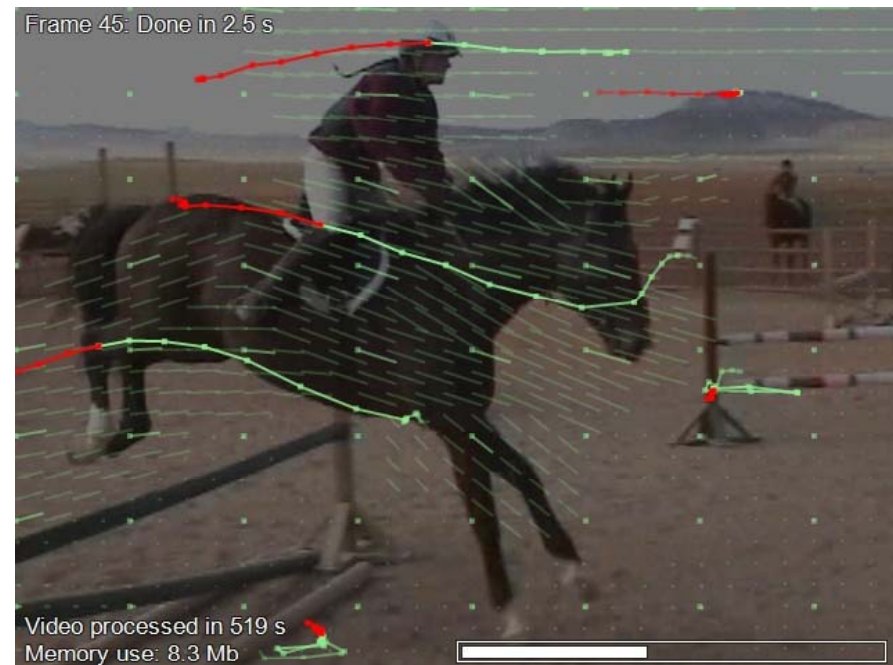
# Extracting Motions from Videos

1. Feature Detection
2. Feature Matching
3. Interpolation
4. Trajectory Construction

- 2b. Background Motion Estimation
- 2c. Background Motion Compensation



**Absolute** Trajectories



**Relative** Trajectories

# Extracting Motions from Videos

1. Feature Detection

2. Feature Matching

3. Interpolation

4. Trajectory Construction

2b. Background Motion Estimation

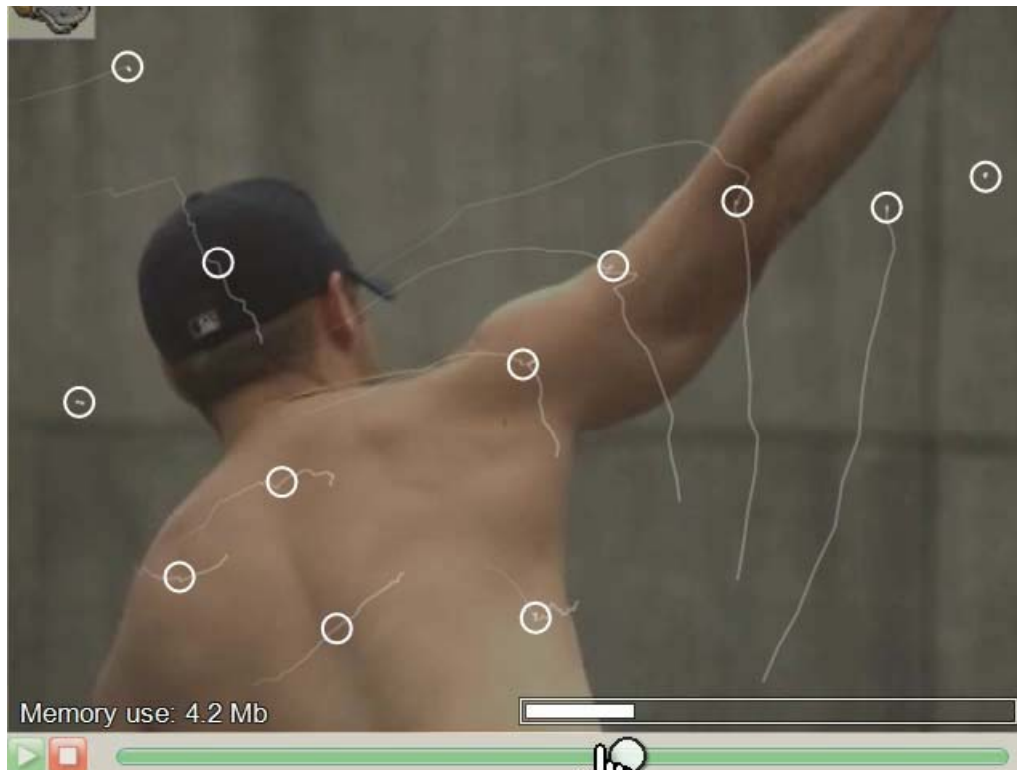
2c. Background Motion Compensation

■ Pre-computed (2-5 sec./frame)

■ Real time

# Extracting Motions from Videos

- Works especially well on:
  - High-quality videos
  - Large, continuous motions
  - Supports deformations



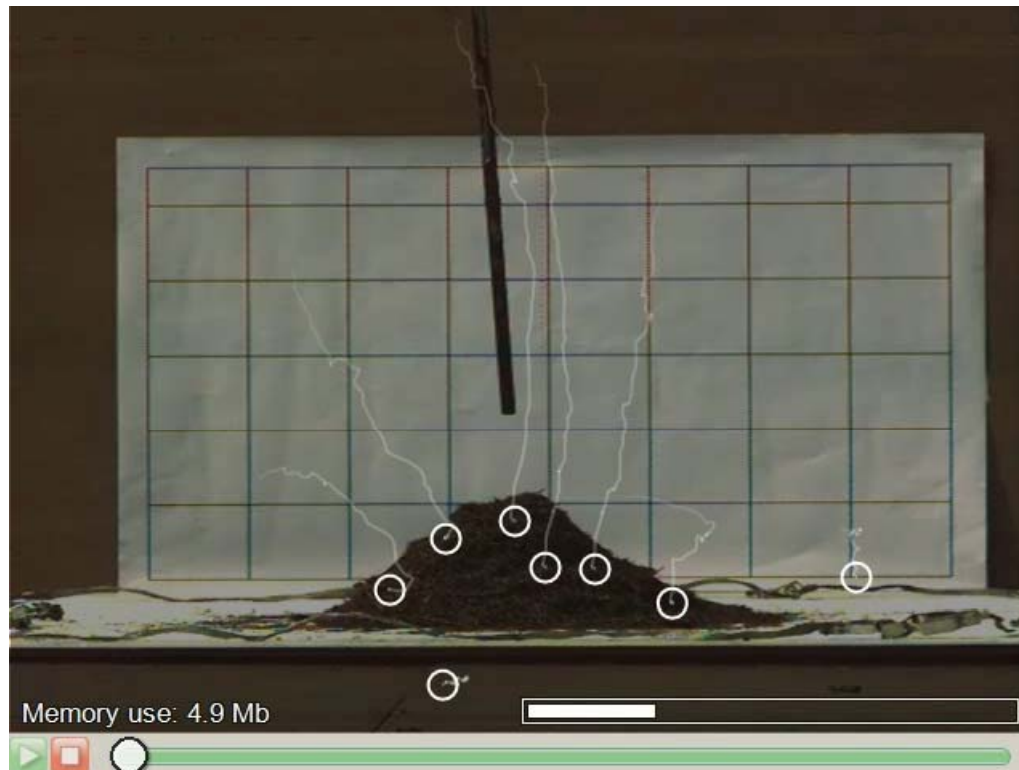
# Extracting Motions from Videos

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# Extracting Motions from Videos

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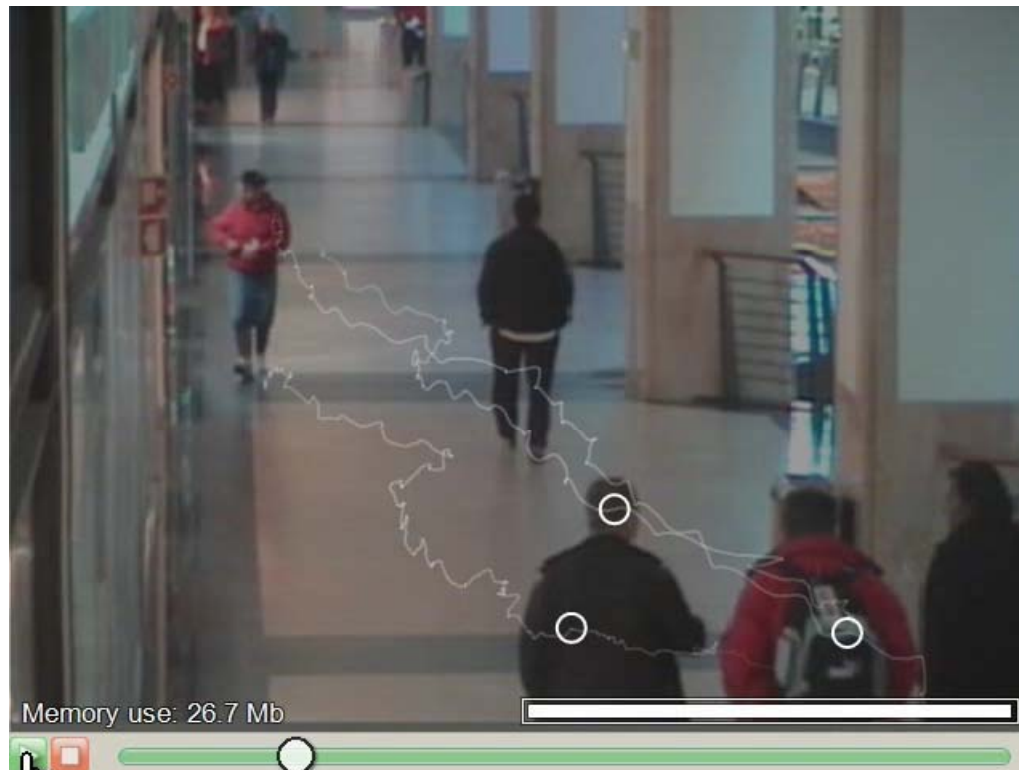




# Extracting Motions from Videos

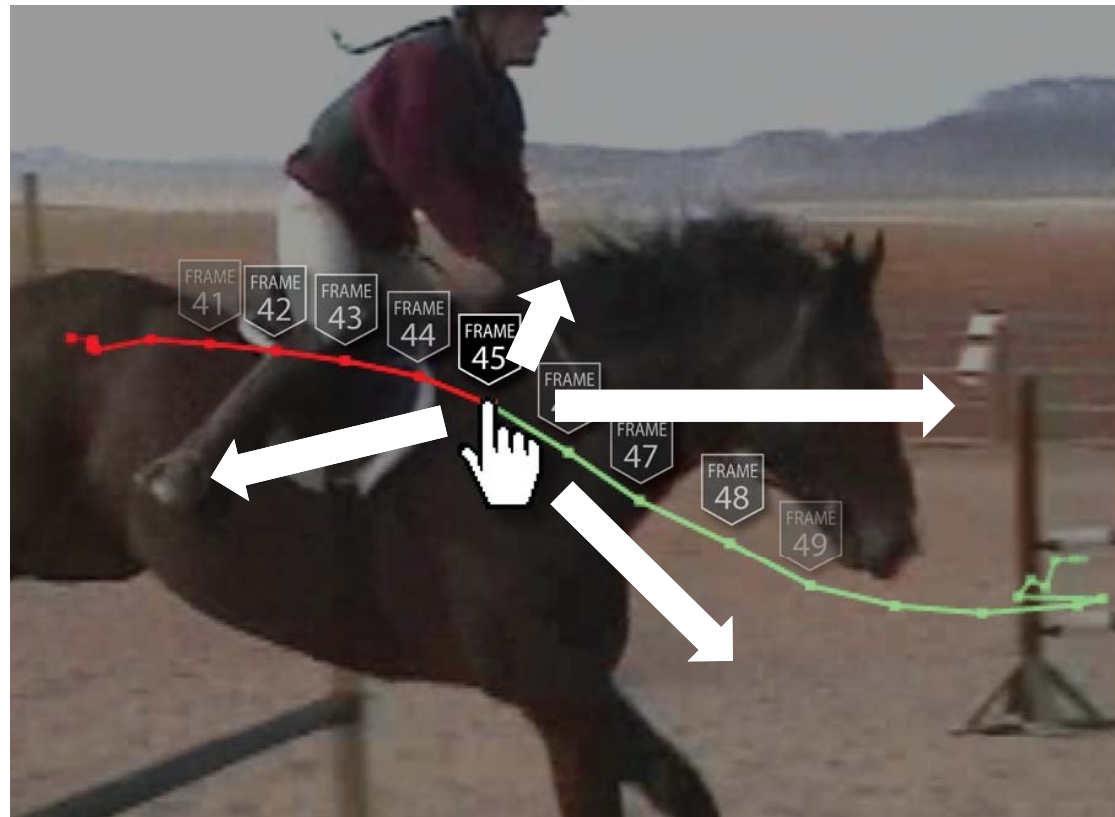
## Limits

- Occlusion



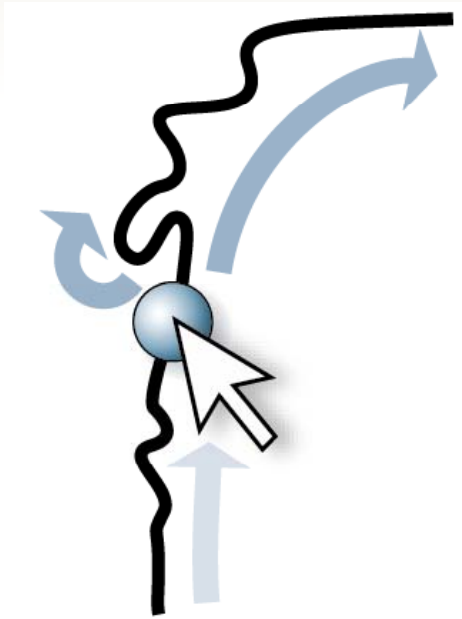
# Extracting Motions from Videos

- Inverse Computation:
  - Location on the curve -> Frame number

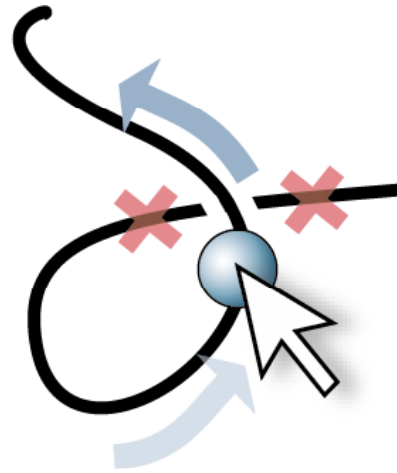




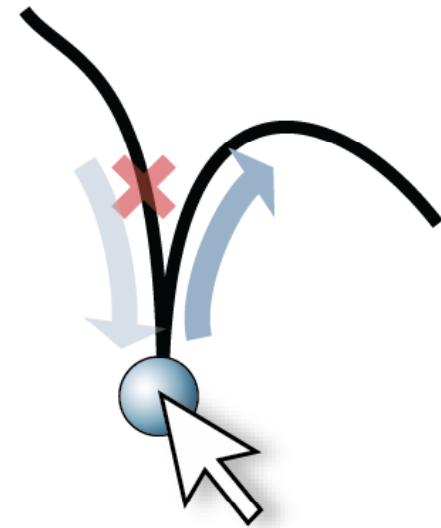
# Curvilinear Dragging Requirements



Multi-Scale  
Navigation



Arc-Length  
Continuity



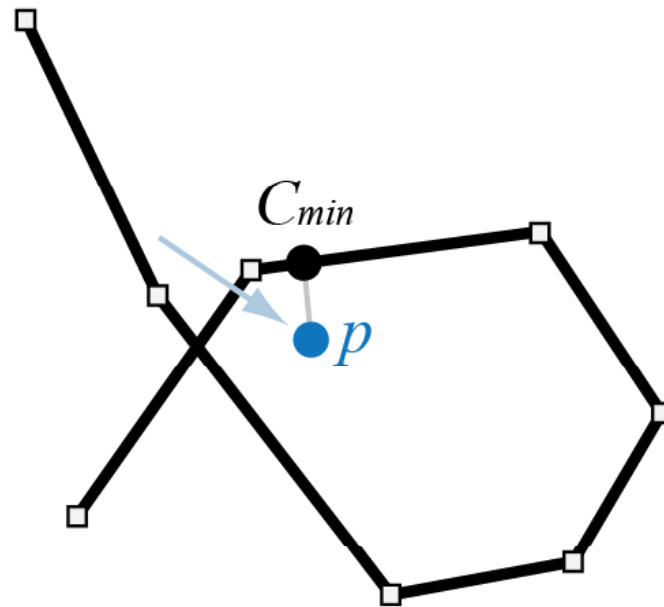
Directional  
Continuity

# Curvilinear Dragging

## Our Solution

- The Closest Point Method

$$D = \sqrt{(p_x - C_x)^2 + (p_y - C_y)^2}$$

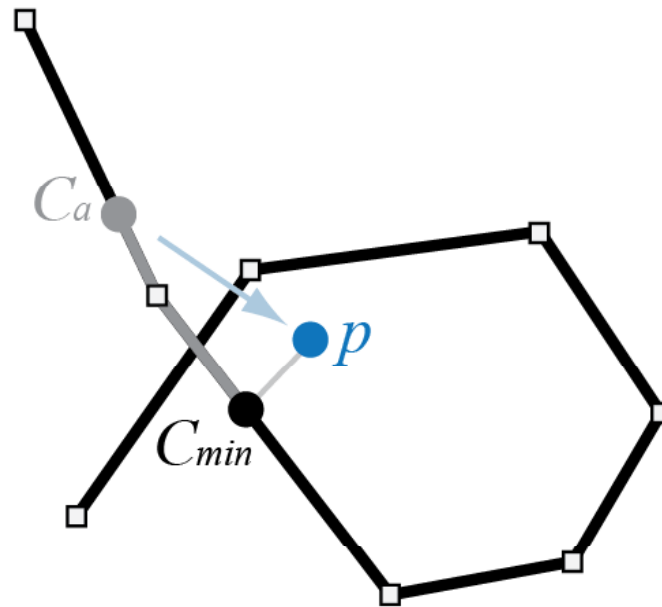


# Curvilinear Dragging

## Our Solution

- The 3D Distance Method

$$D = \sqrt{(p_x - C_x)^2 + (p_y - C_y)^2 + (k \cdot \overline{C_a C})^2}$$

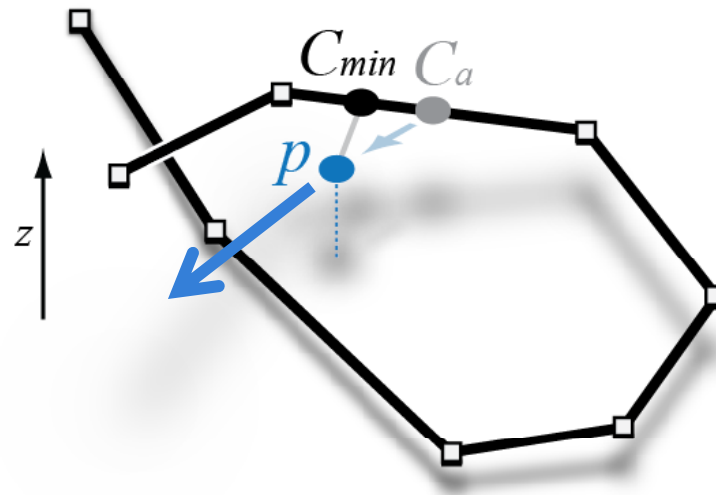


# Curvilinear Dragging

## Our Solution

- The 3D Distance Method

$$D = \sqrt{(p_x - C_x)^2 + (p_y - C_y)^2 + (k \cdot \overline{C_a C})^2}$$

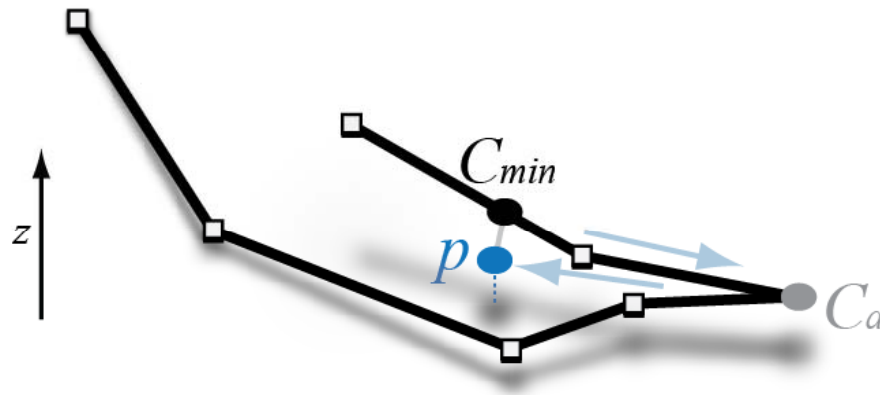


# Curvilinear Dragging

## Our Solution

- The 3D Distance Method

$$D = \sqrt{(p_x - C_x)^2 + (p_y - C_y)^2 + (k \cdot \overline{C_a C})^2}$$

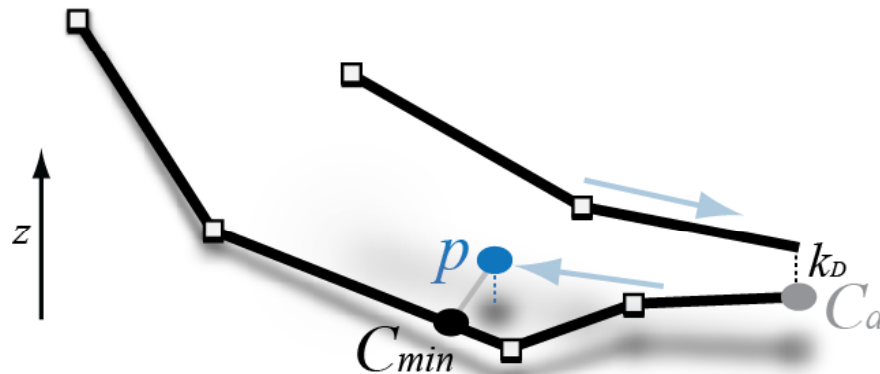


# Curvilinear Dragging

## Our Solution

- The 3D Distance Method

$$D = \sqrt{(p_x - C_x)^2 + (p_y - C_y)^2 + (k \cdot \overline{C_a C})^2} + k_D$$



# Curvilinear Dragging Issues

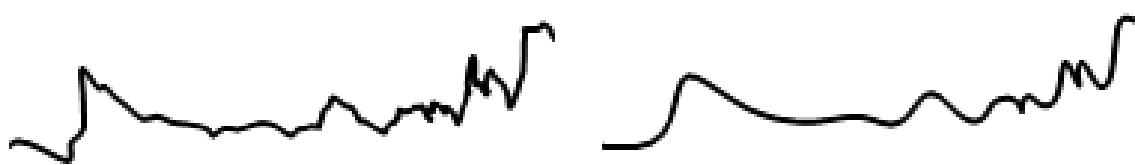
- **Extremely complex curves**

- **Clip curves**



- **Sensitivity to noise**

- **Low-pass filtering [Taubin 95]**





- Direct Manipulation
- RFD
- Motion Extraction
- Curvilinear Dragging
- Video Player Design
- Related Work
- User Study



# DimP

## The Direct Manipulation Video Player

- Design / Demo!

### Trajectory Visualization



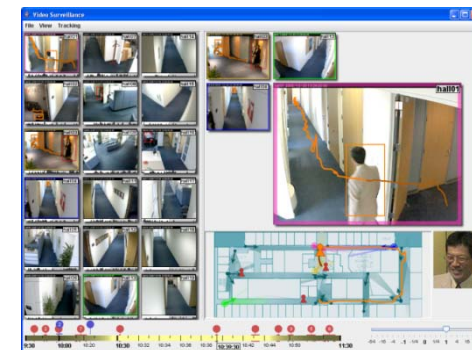
### Background Stabilization



# Dragging Video Content

## Previous (and Current!) Work

- **Similar systems**
  - DRAGRI (2002)
  - Trailblazing
    - Kimber et al. '07
  - DRAGON
    - Karrer et al. '08
- **Visual summaries**
  - Schematic Storyboards
    - Goldman, et al. '06

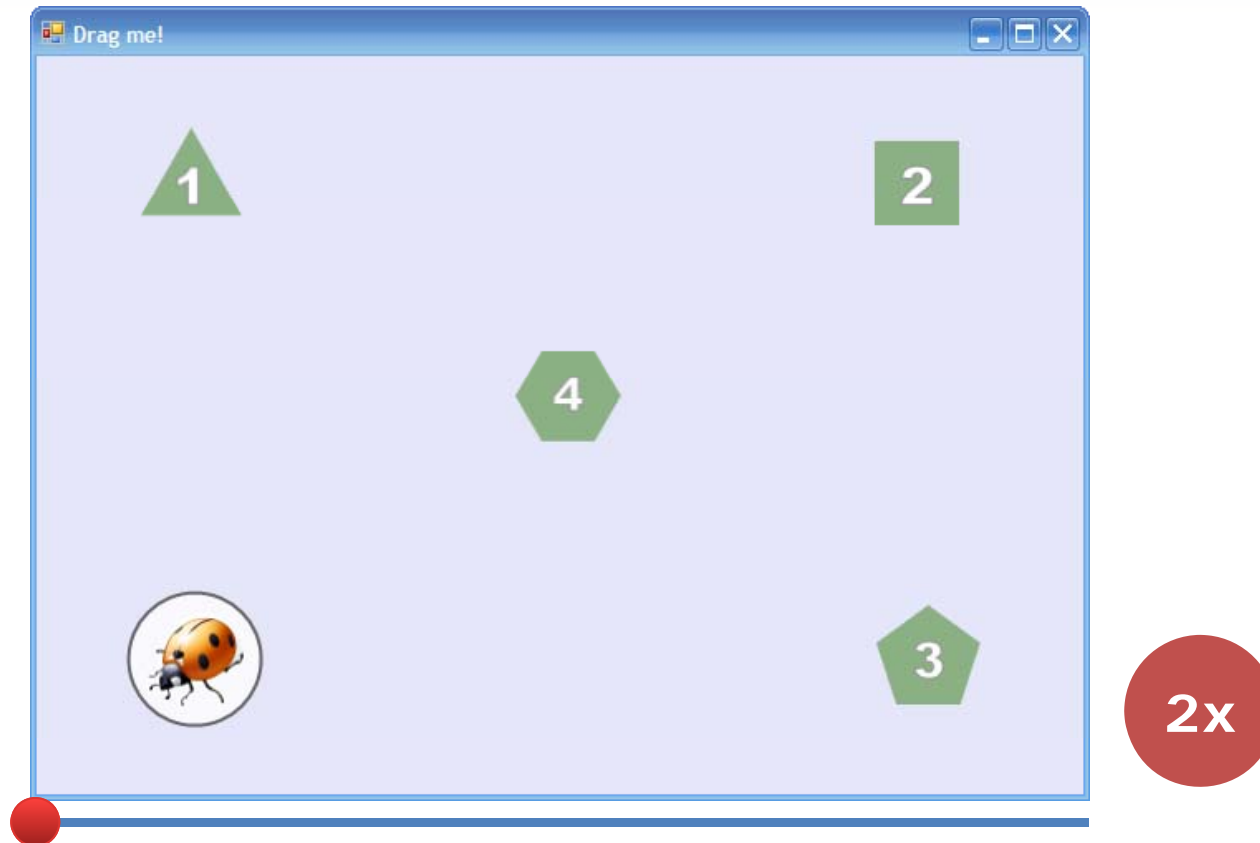


# User Study: Questions

- Advantage in image-space tasks?
- Can users Relative Flow Drag?
- User's preference?

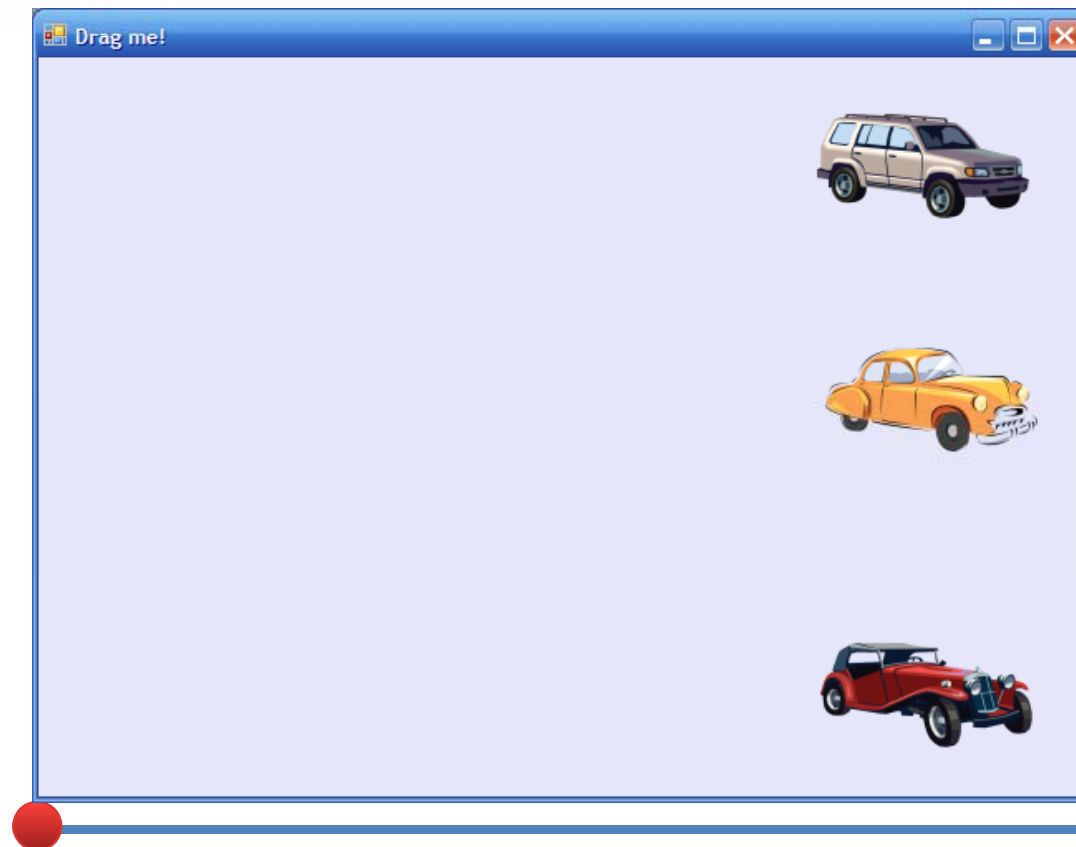
# User Study: Ladybug Task

*“Find the moment in the video when the ladybug passes over marker X”*



# User Study: Car Task

*“Find the moment in the video when car X starts moving ”*

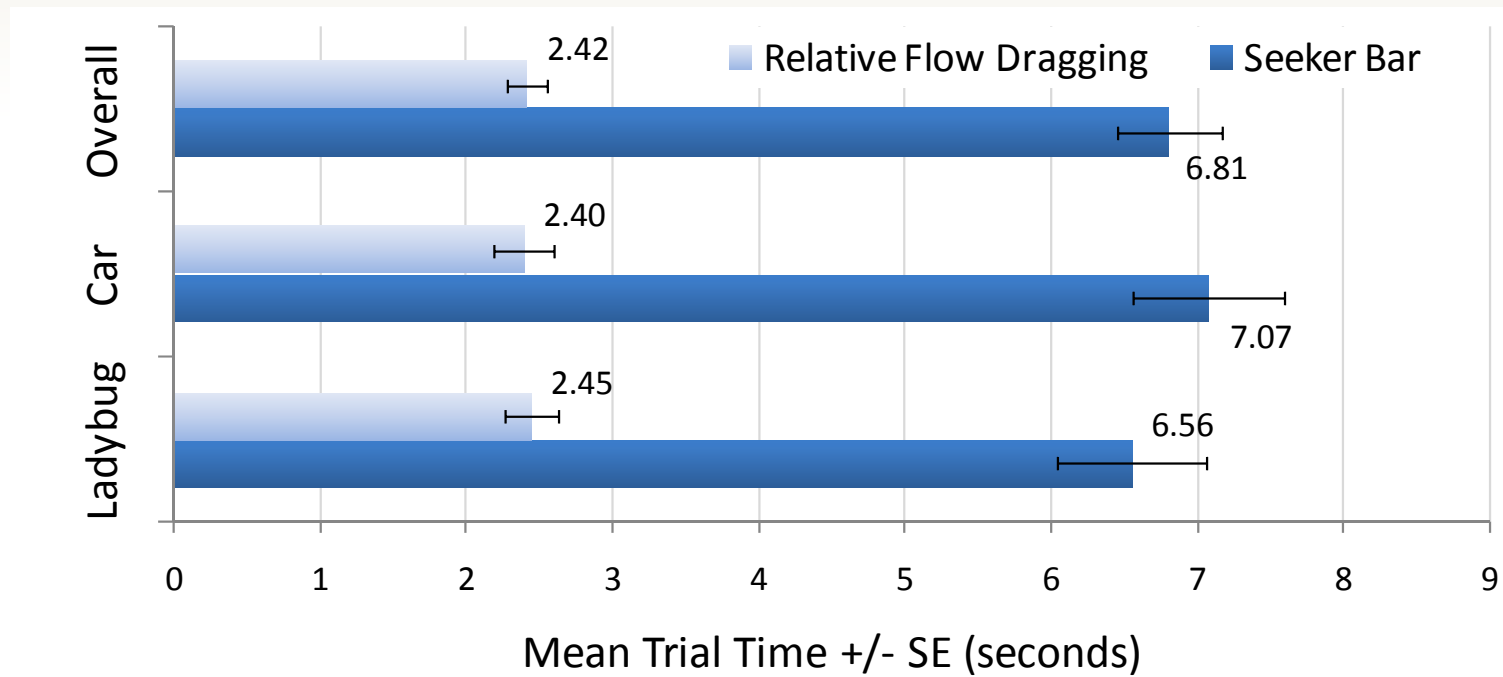


3x

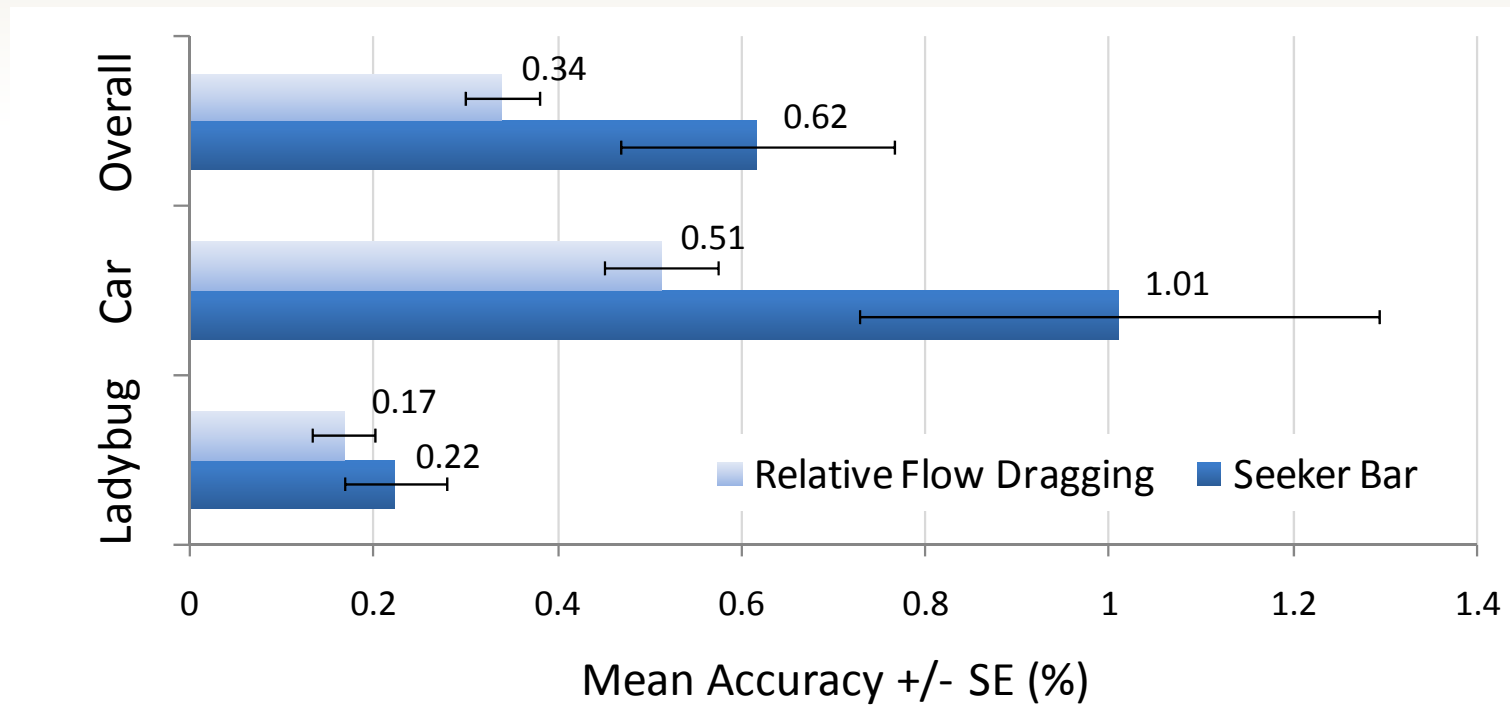
# User Study: Design

- **Within Subjects**
  - 16 Participants
  - 2 Techniques (RFD, Seeker)
  - 2 Tasks (Ladybug, Car)
  - 3 Targets
- **Measured Time, Accuracy**
- **Solicited User's Preference**

# User Study: Time



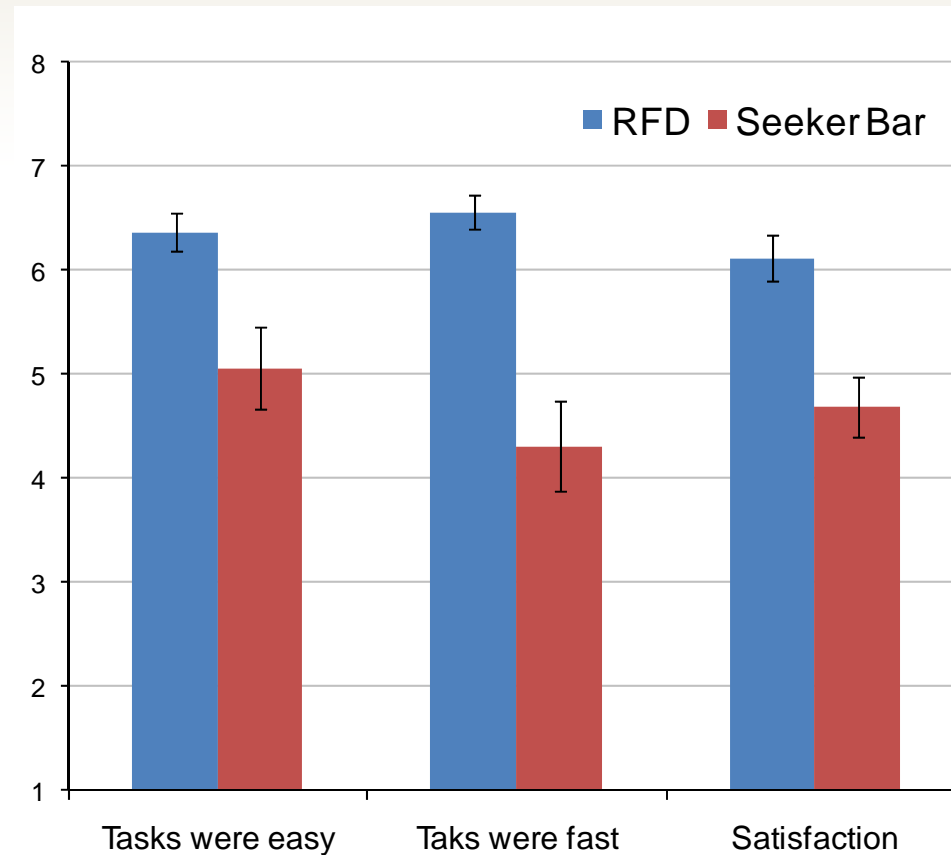
# User Study: Accuracy





# User Study: Preferences

(using a 7-point Likert Scale)



# User Study: Take Aways

- People (Relative Flow) Drag well
- For space-centric tasks, RFD is
  - Faster
  - As precise or more than Seeker Bar
  - As preferred or more than Seeker Bar

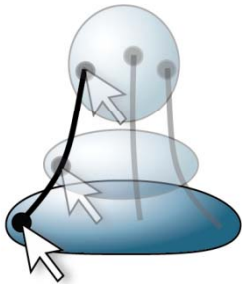
# Conclusion

## & Future Work

- A new way of browsing videos
- Advantages of direct manipulation:
  - Radically different user experience
  - In some cases, more efficient
- Complementary of current tools
- New classes of DM techniques:
  - Curvilinear dragging
  - Flow dragging
  - Relative dragging
- Can be applied to other applications

# Conclusion & Future Work

- Flow Dragging in a 3D Animation Tool  
(Autodesk Maya Extension by Karan Singh)



Animation Timeline →



# Thank You!



# Thank You!

## Video Browsing By Direct Manipulation



Pierre Dragicevic  
Gonzalo Ramos  
Jacobó Bibliowicz  
Derek Nowrouzezahrai  
Ravin Balakrishnan  
Karan Singh

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INRIA, France

[www.aviz.fr/dimp](http://www.aviz.fr/dimp)